

### **FEATURES**

- 2 GHz to 22 GHz
- Compensation for Temperature Drift
- Voltage Regulators for Improved Stability
- 12 Bit Tuning Resolution

#### DESCRIPTION

### PERMANENT MAGNET YTO COMMERCIAL DIGITAL DRIVERS BD-SERIES



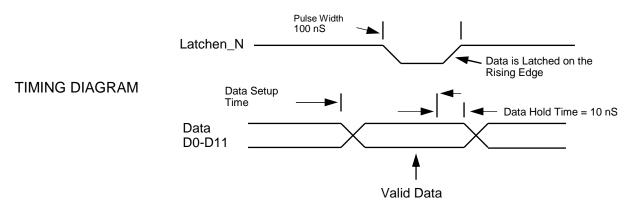
Micro Lambda *MLPM Series* Permanent Magnet YIG Oscillators are available with integrated digital driver circuits. These drivers eliminate the need for customers to design or develop their own driver circuits and sophisticated test and alignment procedures. Integrating a driver at Micro Lambda's factory ensures peak performance. Alignment and compensation with the particular YIG oscillator can be maximized down to the component level.

All drivers in this series provide input voltage regulators and compensation circuits to improve frequency drift. All voltages required by the YIG oscillator, except the heater inputs are supplied by the voltage regulators.

COMMERCIAL DIGITAL DRIVERS	Permanent Magnet YTO's, BD & BG SERIES				
DRIVER INPUT & RESPONSE	SPECIFICATION (0 to + 65 deg. C)				
Tuning Command	Start Word (all 0's) = Lowest Frequency				
	Stop Word (all 1's) = Highest Frequency				
Tuning Resolution	12 BIT Positive Logic (Fmax-Fmin)/4095 Bit Resolution				
	All Data Bits have internal 10k ohm pull-up resistors to +5V				
Tuning Accuracy	+/- 10 MHz				
(excluding hysteresis)					
Tuning Speed (Note 1)	10 mSec for 1 GHz step to within +/-10 MHz.				
	(residual FM is 10 kHz Pk-Pk)				
Main Driver Inputs					
Supply Voltage & Current (Note 2)	+12 V or +15 V +/5 V @ 265 mA, Max.				
	-12 V or –15 V +/5 V @ 165 mA, Max.				
Supply Voltage Pushing	+/- 100 kHz, Max. @ +/5 Vdc				
Supply Voltage Ripple	10 mV Ripple Pk-Pk over 2 kHz to 3 MHz				
Ground	Chassis Ground				
YIG Heater Voltage & Current	+15 Vdc ±4 Vdc @ 300 mA surge for 2 seconds, 50 mA steady state				
-	Polarity independent: ±12 Vdc or ±15 Vdc acceptable				
Latch Enable	LATCHEN_N is a TTL, 5V CMOS control line. It has an internal				
	10k-ohm pull-up resistor to +5 V. It is used to transfer the data on the				
	bus to the digital driver circuit.				
	TTL high = data ignored. Connect to Ground if enable is not required.				
	If the unit is to be used on a computer data bus, the below timing				
	Diagram applies. (All times = Minimum)				
	10 nS rise/fall latch transitions.				

Note 1. Optional 1mS Tuning Speeds Available.

2. Some YIG devices require higher voltages - Check with factory.



# **BD-SERIES** — CONT.

# FM Coil Driver (BG Option)

Voltage	+/- 10 V
Current	+/- 100 mA
Input Impedance	10 k-Ohms
Sensitivity (Note 3)	+/- 2.5 MHz/V
Frequency Deviation	+/- 25 MHz

Note 3: Sensitivity Adjustment Available. Sensitivity Stated is Average Over Frequency Range.

Permanent Magnet YIG Oscillators with Positive Input Digital Drivers				( 0º C to +65º C )		
Model	Frequency	Accuracy	Current	Current	Outline	Outline
Number	GHz	( MHz) *	+12 V (mA)	-12 V (mA)	Drawing	Drawing (BG Option)
Bi-Polar						
MLPM-0204BD	2-4	+/- 10	265	165	61-058	61-058-4
MLPM-0305BD	3-5	+/- 10	265	165	61-058	61-058-4
MLPM-0406BD	4-6	+/- 10	265	165	61-058	61-058-4
MLPM-0507BD	5-7	+/- 10	265	165	61-058	61-058-4
MLPM-0608BD	6-8	+/- 10	265	165	61-058	61-058-4
MLPM-0709BD	7-9	+/- 10	265	165	61-058	61-058-4
MLPM-0810BD	8-10	+/- 10	265	165	61-058	61-058-4
MLPM-0911BD	9-11	+/- 10	265	165	61-058	61-058-4
MLPM-1012BD	10-12	+/- 10	265	165	61-058	61-058-4
MLPM-1113BD	11-13	+/- 10	265	165	61-058	61-058-4
MLPM-1214BD	12-14	+/- 10	265	165	61-058	61-058-4

Model	Frequency	Accuracy	Current	Current	Outline	Outline
Number	GHz	( MHz) *	+15 V (mA)	-15 V (mA)	Drawing	Drawing (BG Option)
MLPW-0812BD	8-12	+/- 10	315	215	61-072	61-098
MLPW-1014BD	10-14	+/- 10	315	215	61-072	61-098
MLPW-1418BD	14-18	+/- 10	315	215	61-072	61-098
MLPW-1822BD	18-22	+/- 10	315	215	61-072	61-098

\* Accuracy includes frequency drift and linearity errors over the temperature range.

